





Dogbot

Name(s): _____

Date: _____

| NGSS GOALS |  BRONZE |  SILVER |  GOLD |  PLATINUM |
|---|--|--|---|---|
| 1. Student work related to this Crosscutting Concept: In this project, we drew and labeled our favorite dogbot design. We explained how the three important parts worked. We described the motion patterns we observed in our dogbot. | | | | |
| Patterns: Observed patterns of forms and events prompt questions about relationships and the factors that influence them. | <ul style="list-style-type: none"> We drew and labeled our dogbot. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Bronze. We labeled the three important parts of our dogbot. We drew at least one motion pattern for one of the dogbot parts. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Silver. We explained how the three important parts worked to create a motion pattern in the dogbot. We drew at least two motion patterns for our dogbot's parts. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Gold. We researched and shared with our teacher or classmates the motion patterns in our dogbot that exist in real dogs. <input type="checkbox"/> |
| 2. Student work related to this Practice: In this project, we built a dogbot and tested different ideas to explore how its eyes, jaws, and tail move. | | | | |
| Developing and Using Models: Use a model to generate data to test ideas about designed systems. | <ul style="list-style-type: none"> We built a working dogbot. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Bronze. We built three cam designs and tested them on our dogbot's eyes. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Silver. We changed our model to test the jaw motion with three different peg positions. We changed our model to test the tail motion with three different pulley set-ups. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Gold. We proposed and tested at least one new design idea for either the eyes, jaw, or tail. <input type="checkbox"/> |
| 3. Student work related to this Practice: In this project, we investigated how the different cam, peg, and pulley settings affected the motion of our dogbot. | | | | |
| Planning and Carrying Out Investigations: Collect data about the performance of a proposed object under a range of conditions. | <ul style="list-style-type: none"> We completed our predictions and observations for our dogbot eye movement experiment. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Bronze. We completed our predictions and observations for our dogbot's jaw experiment. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Silver. We completed our predictions and observations for our dogbot's tail experiment. <input type="checkbox"/> | <ul style="list-style-type: none"> We met Gold. We completed our predictions and observations for at least one new design idea for either the eyes, jaw, or tail. <input type="checkbox"/> |
| Notes: | | | | |